

**THE DEVELOPMENT OF SONIFICATION
MODEL USING PARAMETER
MAPPING TECHNIQUE**



**FACULTY OF COMPUTING AND INFORMATICS
UNIVERSITI MALAYSIA SABAH
2017**

**THE DEVELOPMENT OF SONIFICATION
MODEL USING PARAMETER
MAPPING TECHNIQUE**



ALTER JIMAT EMBUG

UMMS
UNIVERSITI MALAYSIA SABAH

**THESIS SUBMITTED IN FULFILLMENT FOR THE
DEGREE OF MASTER OF SCIENCE**

**FACULTY OF COMPUTING AND INFORMATICS
UNIVERSITI MALAYSIA SABAH
2017**

UNIVERSITI MALAYSIA SABAH

BORANG PENGESAHAN TESIS

JUDUL : _____

IJAZAH : _____

SAYA : _____ SESI PENGAJIAN : _____

(HURUF BESAR)

Mengaku membenarkan tesis *(LPSM/Sarjana/Doktor Falsafah) ini disimpan di Perpustakaan Universiti Malaysia Sabah dengan syarat-syarat kegunaan seperti berikut:-

1. Tesis adalah hak milik Universiti Malaysia Sabah.
2. Perpustakaan Universiti Malaysia Sabah dibenarkan membuat salinan untuk tujuan pengajian sahaja.
3. Perpustakaan dibenarkan membuat salinan tesis ini sebagai bahan pertukaran antara institusi pengajian tinggi.
4. Sila tandakan (/)

SULIT (Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia seperti yang termaktub di AKTA RAHSIA RASMI 1972)

TERHAD (Mengandungi maklumat TERHAD yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan)

TIDAK TERHAD

Disahkan oleh:

(TANDATANGAN PENULIS)_____
(TANDATANGAN PUSTAKAWAN)

Alamat Tetap: _____

(NAMA PENYELIA)

TARIKH: _____

TARIKH: _____

Catatan:

*Potong yang tidak berkenaan.

*Jika tesis ini SULIT dan TERHAD, sila lampirkan surat daripada pihak berkuasa/organisasi berkenaan dengan menyatakan sekali sebab dan tempoh tesis ini perlu dikelaskan sebagai SULIT dan TERHAD.

*Tesis dimaksudkan sebagai tesis bagi Ijazah Doktor Falsafah dan Sarjana Secara Penyelidikan atau disertai bagi pengajian secara kerja kursus dan Laporan Projek Sarjana Muda (LPSM).

DECLARATION

I hereby declare that the material in this thesis is my own except for quotations, excerpts, equations, summaries, and references, which have been duly acknowledged.

20 July 2017

Alter Jimat Embug
MI1321001T



UMS
UNIVERSITI MALAYSIA SABAH

CERTIFICATION

NAME : ALTERJIMAT EMBUG

MATRIC NO : MI1321001T

**TITLE : THE DEVELOPMENT OF SONIFICATION MODEL USING
PARAMETER MAPPING TECHNIQUE**

DEGREE : MASTER OF SCIENCE (INFORMATION TECHNOLOGY)

VIVA DATE : 22 FEBRUARY 2017

 **CERTIFIED BY:**
1. SUPERVISOR Signature
Assoc. Prof. Dr. Ag Asri Hj. Ag Ibrahim
UMMS
UNIVERSITI MALAYSIA SABAH

ACKNOWLEDGMENT

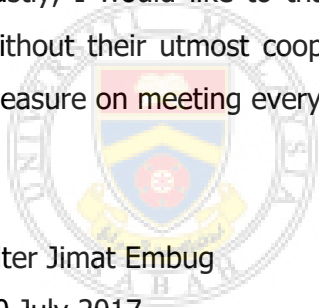
First and foremost, I would like to express my deepest gratitude and appreciation to my supervisor, Assoc. Prof. Dr. Ag Asri Hj. Ag Ibrahim for all his advice, guidance and support in this research that leads to the completion of this thesis. Without his support and motivation, I would not be able to finish this thesis within given time.

Next, I would like to thank my family for giving me the strengths and motivation in the process of completing my research. Their love and endless support helps me to become a better person. Also, many thanks to my friends who have supported me during the writing of this thesis.

Lastly, I would like to thank all the participants that make this research happen, without their utmost cooperation, this research could not be completed. It was a pleasure on meeting everyone throughout the process of this research.

Alter Jimat Embug

20 July 2017



UMMS
UNIVERSITI MALAYSIA SABAH

ABSTRACT

Most of the instructions given by trainers or therapists in body movements, such as walking, turning, rising arms or legs are mostly done through voice instructions or touches. This does not poses much problem to ordinary people as they can see the action at the same time. To follow these instructions without visual may cause confusion in terms of actions and directions. Unfortunately, there was no other option for the visual-impaired persons. Thus, this research studies on transforming those voices and touches form of instructions into non-speech sound instructions. The method involves transforming 3-dimensional data of body movements (kinematics) into sounds. This research expects to provide audio aid, and the user should be able to follow the exact body movements of another person or instructor without any speech commands or instructions. The novel contribution of this research is to produce a sonification model (converting the data into sound) that represents the actions and directions of the body movements in 3-dimensional space. Parameter Mapping is used as the conversion approach, where the movement properties will be mapped to sound properties. The parameter mapping involves three transformation processes - data, acoustics parameters and sound representations. This research used the Kinect (Microsoft Xbox 3D movement sensors) as the live 3D movements input data stream. Kinect technology was intentionally used due to its readiness and low cost. Experiments were conducted to examine the effect of audio 3D movement knowledge and training through the number of success performance between groups. The result demonstrates that given knowledge and training enhances the number of success performance compare to the control group. In Conclusion, the results show that the 3D hand movements can be represented using non-speech sound. From the finding, training is required beforehand to increase the ability to interpret the proposed 3D sound design.

Keywords: Sonification, 3D Body Movement, Parameter Mapping.

ABSTRAK

PEMBANGUNAN MODEL SONIFICATION MENGGUNAKAN TEKNIK MENYAMBUNG PARAMETER

Kebanyakan arahan pergerakan yang diberi oleh jurulatih atau pakar terapi dalam pergerakan badan, seperti berjalan, berpusing, menaikkan tangan atau kaki adalah dilakukan melalui arahan suara atau sentuhan. Ini tidak memberi masalah kepada orang normal kerana mereka boleh melihat. Namun, untuk mengikuti arahan ini tanpa melihat, ia boleh menyebabkan kekeliruan dari segi pergerakan badan. Malangnya, tiada pilihan bagi orang-orang yang buta. Oleh itu, kajian ini mengkaji bagaimana untuk menggantikan arahan berbentuk suara dan sentuhan kepada arahan berbentuk bunyi bukan berbentuk pertuturan. Kaedah ini mengubah data 3 dimensi pergerakan badan (kinematik) kepada bentuk bunyi. Kajian ini berharap hanya dengan mendengar bunyi, seseorang itu akan dapat mengikuti pergerakan sebenar tubuh orang lain atau pengajar tanpa apa-apa arahan suara atau arahan. Novelti kajian ini adalah untuk menghasilkan model sonification (menukarkan data kepada bentuk bunyi) untuk mewakili tindakan dan arahan pergerakan badan dalam ruang 3 dimensi. Pendekatan yang di gunakan adalah pemetaan parameter, dimana sifat-sifat pergerakan akan dipetakan kepada elemen bunyi. Pemetaan parameter melibatkan 3 proses transformasi- data, parameter akustik dan representasi bunyi. Keberkesanan pendekatan ini adalah bergantung kepada 3 proses transformasi tersebut. Kajian ini menggunakan Kinect (sensor pergerakan 3 dimensi Microsoft Xbox), sebagai aliran input pergerakan 3D. Peranti ini digunakan di dalam kajian oleh kerana kadar kesediaan dan kos rendah. Eksperimen telah dilakukan untuk mengkaji kesan pengetahuan dan latihan berdasarkan audio terhadap bilangan prestasi kejayaan antara kumpulan. Hasilnya menunjukkan dengan memberi pengetahuan dan latihan, ia meningkatkan bilangan prestasi kejayaan berbanding dengan kumpulan kawalan. Kesimpulannya, pergerakan tangan berbentuk 3D boleh di wakili menggunakan bunyi bukan pertuturan. Dari hasil kajian tersebut, latihan diperlukan terlebih dahulu untuk meningkatkan keupayaan untuk mentafsir reka bentuk bunyi 3D yang dicadangkan.

LIST OF CONTENTS

TITLE	Page
DECLARATION	ii
CERTIFICATION	iii
ACKNOWLEDGMENT	iv
ABSTRACT	v
ABSTRAK	vi
LIST OF CONTENTS	vii
LIST OF TABLES	x
LIST OF FIGURES	xi
LIST OF APPENDICES	xii
CHAPTER 1: INTRODUCTION	1
1.1 Introduction	1
1.2 Problem Statement	2
1.3 Research Goal	3
1.4 Objective	4
1.5 Research Question	4
1.6 Research Hypothesis	5
1.7 Significant of Study/Contribution	5
1.8 Research Structures	6
1.9 Summary	8
CHAPTER 2: LITERATURE REVIEW	9
2.1 Introduction	9
2.2 Sonification	9
2.2.1 Audification	10
2.2.2 Parameter Mapping	11
2.2.3 Model-Based Sonification	11
2.2.4 Earcons	11

2.2.5	Auditory Icons	12
2.3	Parameter Mapping Sonification	12
2.3.1	Polarity	14
2.3.2	Scaling	14
2.3.3	Auditory/Sound Design Approach	14
2.4	3D Body Movement	16
2.4.1	Exercise	17
2.4.2	Playing	17
2.4.3	Sports	18
2.5	Range of Motion	19
2.5.1	Motion Capture Implementation	21
2.6	Non-Speech Sound	22
2.7	Sound Synthesis System	22
2.8	Conclusion	22
2.9	Summary	23
CHAPTER 3: RESEARCH METHODOLOGY		24
3.1	Introduction	24
3.1.1	Research methods	25
3.2	Overview of Sonic Motion Follow (SMF) process	26
3.3	General sonification design	27
3.4	Overview of parameter mapping sonification technique of 3D Body movements	28
3.5	Designing and implementation of data transformation	31
3.5.1	Mapping design of sound properties with x, y, z-axis	31
3.5.2	Model sound properties	34
3.6	Software and hardware	35
3.7	General Data flow	35
3.8	Sonic Motion Follow Model	37
3.9	Sonification and OSC	41
3.10	Summary	41
CHAPTER 4: EMPIRICAL STUDY OF PARAMETER SONIFICATION DESIGN OF 3D BODY MOVEMENTS.		42
4.1	Introduction	42
4.2	Dependent and independent variables	42

4.2.1	Compare experiments	44
4.3	Material and method	45
4.3.1	Participants	46
4.3.2	Experiment setup.	46
4.3.3	Procedure	46
4.3.4	Control group	48
4.3.5	Test group 1	49
4.3.6	Test group 2	50
4.4	Potential Threat	50
4.5	Data analysis	50
4.6	Result and research finding.	51
4.6.1	Control group	51
4.6.2	Test group 1	55
4.6.3	Test group 2	57
4.7	Compare experiments	60
4.7.1	Compare experiment between group A and B	60
4.7.2	Compare experiment between group A and C	62
4.8	Discussion	65
4.9	Summary	66
CHAPTER 5: CONCLUSION		67
5.1	Introduction	67
5.2	Conclusion	68
5.3	Future Work	70
REFERENCE		71
APPENDICES		80

LIST OF TABLES

	Page	
Table 4.0	Different groups with different conditions	43
Table 4.1	Overview summary for pair groups	44
Table 4.2	Experimental task {M1-Movement 1... M5-movement 5}	46
Table 5.1	The result of single hand task for position and motion in group A	52
Table 5.2	The result of both hands task for position and motion in group A	53
Table 5.3	The result of single hand task for position in Group B	56
Table 5.4	The result of Both hand task for position in Group B	56
Table 5.5	The result of single hand task for position and motion in group C	58
Table 5.6	The result of both hands task for position and motion in group C	59
Table 5.7	Mean compared between groups A and B for single hand position	61
Table 5.8	Mean compared between groups A and B for both hands position	61
Table 5.9	Mean compared between groups A and C in single hand position	62
Table 5.10	Mean compared between groups A and C in single hand motion	63
Table 5.11	Mean compared between groups A and C in both hands position	63
Table 5.12	Mean compared between groups A and C in both hands Motion	64

LIST OF FIGURES

		Page
Figure 1.1	Research structure	6
Figure 2.1	Map for a general design process of PMSon	13
Figure 2.2	An arrangement of the multidisciplinary of "aiding movement"	16
Figure 2.3	Movement in the shoulder complex. A; Range of motion (ROM) of the shoulder. B; Axes of arm elevation	20
Figure 3.1	The subject in front was able to guess the trainer right-hand position	26
Figure 3.2	The general structure of sonifying 3D body movement	24
Figure 3.3	Overview of parameter mapping sonification technique of 3D Body movements	26
Figure 3.4	Human Shoulder Range of Motion Planes	31
Figure 3.5	Mapping X axis with sound panning	32
Figure 3.6	Y axis mapping with frequency	33
Figure 3.7	Mapping L (displacement) with tempo	33
Figure 4.1	The general experiment setup	35
Figure 4.2	The overview of SMF model flow	37
Figure 4.3	From left to right show before and after transposition	39
Figure 4.4	From left to right shows before and after transposition	40
Figure 4.5	Five hand positions	47
Figure 4.6	Five hand positions that contain in the motion	47
Figure 4.7	Five hand position using both hands	48
Figure 4.8	Five hand positions that contain in the motion using both hands	48
Figure 4.9	2D mapping plane of plane x, y and plane x, z	49

LIST OF APPENDICES

		Page
Appendix A	Supercollider coding for mapping NIMATE with SUPERCOLLIDER	80
Appendix B	Supercollider Coding Sample for Second Experiment	85



UMS
UNIVERSITI MALAYSIA SABAH

CHAPTER 1

INTRODUCTION

1.1 Introduction

Rehabilitation requires a longer time to recover and required a lot of money in term of transportation and also time-consuming often last to 3 hours a day, 5 to 6 days a week for patients who stay in a facility (Post-Stroke Rehabilitation, 2014). For the normal persons, they may choose to do the rehabilitation at home, using video chat as the medium of communication with the trainer. The trainer no longer required to be present in the patient vicinity, which makes it way convenient called telerehabilitation (John Wiley & Sons, 2005) (Lisa Keaton, et al., 2011). Through the video chat, the patient and trainer can communicate, give feedback and understand each other. Unfortunately, patient who is blind that undergoes the same rehabilitation process have limited option compared to the normal people. They were unable to do the rehabilitation at their home, and they may have to spend more (in term of transportation) for each physiotherapy sessions. Imagine the difficulties on trying to follow the prescribed exercise with closed eyes.

In a real-time situation, the therapist often may distracted from the contact with the patient due to having to operate the (visual) menu system and examining the (visual) results (Pauletto & Hunt, 2004) (Pauletto & Hunt, 2006) (Pauletto S. &, 2009). The question is; do we have any alternatives? Is there a way to instruct a person to move their body without using any speech and touch instructions? It would be a good idea, if a patient could understand and able to follow the body movements of the therapist (actions and directions) by only listening to the sounds that represent the movements.

Most of the previous researches were using high cost equipment such as Vicon motion tracking studio (Vicon, 2014) or requires to be developed, mostly were prototype using accelerometer to capture the data intended to be sonified.

This research may potentially produce an assistive tool for the disabled person (blind) and potentially improve the data analysis in physiotherapy. This tool may also motivate a much more fun exercise. Thus, this research focused on designing a model to transform the 3D body movement (hands) into the non-speech sound to represent the motion using readily available low cost device dubbed "SonicMotionFollow". For this research, the model is defined as the general process of transforming and mapping the raw data and finally produces a non-speech sound that represents the data. Three types of experiments were conducted to test the hypothesis.

1.2 Problem Statement

These are the statements of the problem of this research;

1) Blind people that undergo physiotherapy rehabilitation have limited option compared to normal people.

Normal people, they may choose to do the sessions at home by communication via video chat called telerehabilitation (John Wiley & Sons, 2005) (Lisa Keaton, et al., 2011). Unfortunately, blind patients have limited option to do the sessions at their own home, and they may have to spend more for each session they went to at the physiotherapy rehabilitation facility (Post-Stroke Rehabilitation, 2014). Even though they may have friends or family that can assist them in the exercise, but it still may be too confusing to follow the action and movement by the therapist. Imagine the difficulties on trying to follow the prescribed exercise with closed eyes. It would be great if there is a tool that can assist them when performing the rehabilitation exercise in their own home.

2) Prescribe exercise can be a difficult task.

In the rehabilitation service, one of the most valuable tools for the physiotherapy profession was the therapeutic exercise that requires on learning a complex motor skill (Kisner & Lynn, 212), which can be a difficult task. The prescribed exercise program was often performed with the manual instructions by the therapist. This exercise requires more practice on recreating the movement, proven difficult even with the help of visual aids and coaching. To follow these exercises without visual will be confusing and may cause mislead towards actions and directions. Unfortunately, there was no other option for the blind people. Imagine if the information about the motion can be conveyed into a sound that can assist the users while performing an exercise task. It will be exciting and fun.

3) Therapist may often distract from contact with the patient.

In a real-time situation, the therapist may often distract from contact with the patient due to having to operate the monitor menu system and examining the (visual) results (Pauletto & Hunt, 2004) (Pauletto & Hunt, 2006) (Pauletto S. &, 2009) It would be good if the menu system can be transformed into a sound representation, then the trainer will be able to focus more on the patient.

4) Using a prototype equipment to extract 3D coordinate human movements

Some researches were required to develop at least a prototype such as one that used the accelerometer to capture data to be sonified. Thus, this research will use a readily available device to capture the data to be sonified on representing the actions and directions of body movements in 3-dimensional spaces.

1.3 Research Goal

The research goal was to design, develop and evaluate the model of non-speech sounds to represent the action and direction of the 3-dimensional body movements through parameter mapping sonification technique.

1.4 Objective

There are three objectives of this research;

1) To collect and review the previous literature works

This process is to define the key terms and to identify the potential sources of information for this study.

2) To design and develop the sonification model for transforming 3D body movement using parameter mapping technique

A series of experimental research were conducted and a sonification model was produced. The selected coordinate (x, y, and z-axis) were mapped to the three sounds properties. A low-cost system was also developed and used as the platform of the research experiment.

3) To evaluate the result of the design model.

Experimental research was conducted to test the effectiveness of the design model using different types of motions.

1.5 Research Question

In general, the research intends to answer the following question: is it possible to sonify the human 3D motions information using parameter mapping technique to help the users to understand the movements only by listening? The design inspection was referred from the systematic usability inspection approach (Asri & Hunt, 2007). There are three research questions for this research;

1) How to transform and manipulate the data from Kinect technology into a new form of sonifiable data?

Some raw data may need to be filtered before it can be used for the mapping process and often requires to be changed into something more suitable for a sound transformation, which refers to the data transformation. Some of it then may require to be scaled into more suitable range of scale, for example: from range 0 to 1 or change in decimal place. The raw data coordinate was calculated based on the center point (head).

The head was chosen as the center point because the human perceives sounds from their left and right ears.

2) How to transform the sonifiable data into the acoustically ready data? This process was to transform the sonifiable data into the acoustic parameter data called acoustics ready data, where the sonifiable data was suitable to be used in the mapping process. This data then will be mapped into the three sound properties, which is the frequency, volume, and tempo. More explanations for the mapping process are described on Chapter 3.

3) How to combine and manipulate the acoustically ready data into the final sound transformation to represent the actions and directions of 3D body movement?

The outputs of the transformation are then converted into the sound which can be listened using a headphone. Final sound transformation is referred as the process of manipulating the output from the acoustic parameter mapping transformation. Further details are presented in the model of the design in the Chapter 3.

1.6 Research Hypothesis

Actions and directions of the 3-dimensional body movements can be effectively represented using the non-speech sounds through parameter mapping technique.

1.7 Significant of Study/Contribution

The main focus of this research was to produce an effective sonification technique to convert the data (signified) into a sound (signifier). In this research, the data to be "signified" is the 3D body movements, and the "signifier" is the sound to represent the 3D body movements.

1.8 Research Structures

The approach of this study could be divided into four different sections. Figure 1.1 shows the research processes: (1) literature review, (2) sonification of 3D body movement, (3) experimental design, (4) and the result analysis.

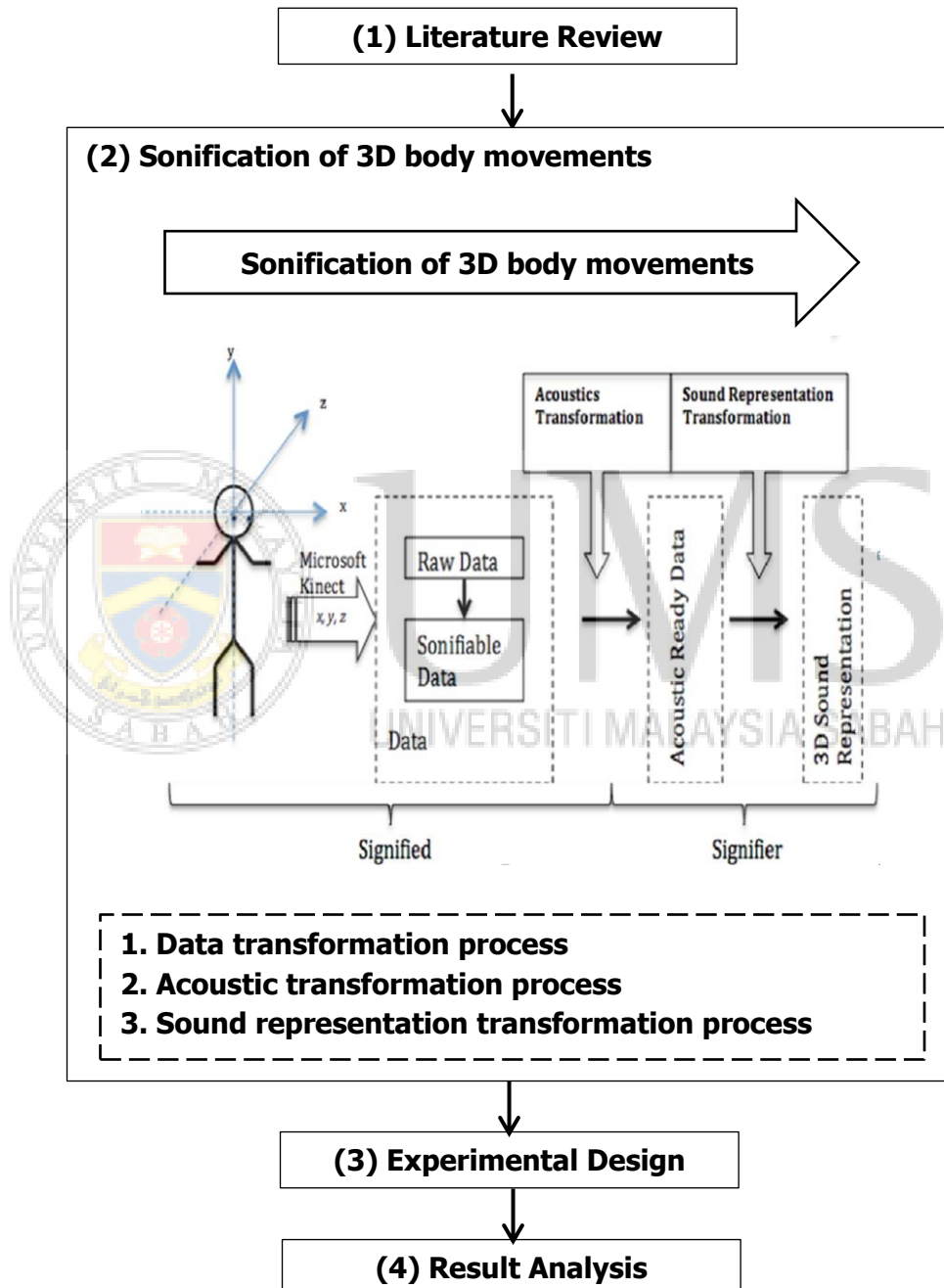


Figure 1.1: Research structure (Ibrahim & Embug, 2014)

1) Literature review

During this phase, previous researches based on the keyword of: Sonification; kinematics; 3D movements; Parameter Mapping were selected and reviewed. The reviews also involve the understanding on how the human perceive sounds. This process is described in the Chapter 2.

2) Sonification of 3D body movement

This part describes the process of data transformation the raw data taken by using Kinect 360, then processed for transformation to a more suitable form for the mapping process and finally produced a sound that properly represents the human motion. In addition, this section explains how the sound properties are mapped and shows the overview design of the model "SonicMotionFollow". This process is described in the Chapter 3.

3) Experimental design

This section defines and formulates the hypothesis, dependent and independent variable of the study. It also includes the detailed explanation of the model "SonicMotionFollow", the raw data collection process, the data transformation process, and the mapping process. Possible threats that may affect the experiments and the steps involved in conducting the experimental study were also listed. Selection of the sample of subjects, identification and controlling the nonexperimental factors are conducted along with the construction of the outcome measurement. Pilot-testing was also conducted and the duration of the experiments was determined in this phase. The process is described in the Chapter 4.

4) Result Analysis

This phase involves the analysis and the interpretation of the collected quantitative data. The result findings will be discussed and concluded. This process is described in the Chapter 5.

1.9 Summary

A model of transforming the 3D body movement into sounds was developed to enable the blind patients to understand the rehabilitation training and learning motion through listening. It may help the therapist to examine their patient exercise result with less distraction. The next chapter explains the literature reviews that are related to this three keywords; sonification, 3D body movement and parameter mapping. The design or model from the related researches is reviewed based on the criterion such as: the type of sound properties, possible sound properties, and different types of data for mapping technique. The review also intends to understand the process of parameter mapping as well as how to transform raw data into sonifiable data.



UMS
UNIVERSITI MALAYSIA SABAH

CHAPTER 2

LITERATURE REVIEW

2.1 Introduction

The previous chapter stated the problem that needs to be studied on the growing demand of global physiotherapy rehabilitation and the challenges for the blind patients to follow the prescribed programs. In addition, in most real-time situation, the therapist often may be distracted from the contact with the patient due to having to operate the (visual) menu system. Also, the researcher has explained about the type of research question need to be answered, and the objective that needs to be achieved.

In this chapter, the thesis reviews on the three related keywords; sonification, 3D body movement and parameter mapping. Then, the chapter reviews on the related literature work and identify the type of data and the sound properties that were used in those researches.

2.2 Sonification

What is Sonification? Sonification was defined as "the representation of information using non-speech sound to help in understanding of data or processes by listening" (Kramer G. , 1994) or "the transformation of data relations into perceived relations in an acoustic signal for the purposes of facilitating communication or interpretation" (Kramer G. , 1994). Referring to these definitions, the sonification applications should have the following three main elements; the goal, tasks and objectives to achieve (e.g. interpretation, communication, emotion etc.); Input (data) and output (non-speech sound); and the technique(s) of transforming data into sound

The sound can be produced by using a synthesizer and designed by manipulating its perceptual qualities such as the pitch, timbre, loudness, spatial location, and extent. Sonification techniques is the process of manipulating the perceptual qualities and changing data into sound. It is important to understand the existing sonification technique before designing a framework or model.

There were several existing sonification techniques that were currently available and most widely accepted among the research community which was described in detail in the Sonification Handbook (Dombois F. a., 2011.), audification (Dombois F. , 2001) (Dombois F. a., 2011.), parameter mapping (Grond & Berger, 2011; Kramer G. , 1994), model based sonification (Hermann, 2004; Hermann, 2011.), earcons (McGookin & Brewster, 2011) and auditory icons (Brazil & Fernstorm, 2011)

2.2.1 Audification

Audification is the direct translation of a data waveform into sound (Dombois & Eckel, 2011) and the series of data might not even belong to the sound domain. A common way of displaying this visually would be the Cartesian graph. If the visualized data have a wave-like shape, for example an EEG signal, audification would mean to attribute their values to air pressure and transferring the result to a loudspeaker, whereby the data then become audible.

The aim behind this media shift, as in all the sonification techniques, is that the other mode of representation discloses or makes emerge aspects of the data that might not have been discovered before (Dombois & Eckel, 2011). The most profound audification technique was carried out by Pauletto and Andy Hunt (2005), they tried to understand the advantage and the disadvantages of audification in general (Pauletto & Hunt, 2005).

Audification also contributes in the medication domain such as the work by Jesus Olivan, Bob Kemp and Marco Roessen (Olivan, Kemp, & Roessen, 2004) that investigates on the EEG sleep recordings. Moreover, audification were also used in seismology (Meier & Saranti, 2008), physics (Martini, Hermann, Anselmetti, & Ritter, 2004) and stock market (Frysinger, 1990).